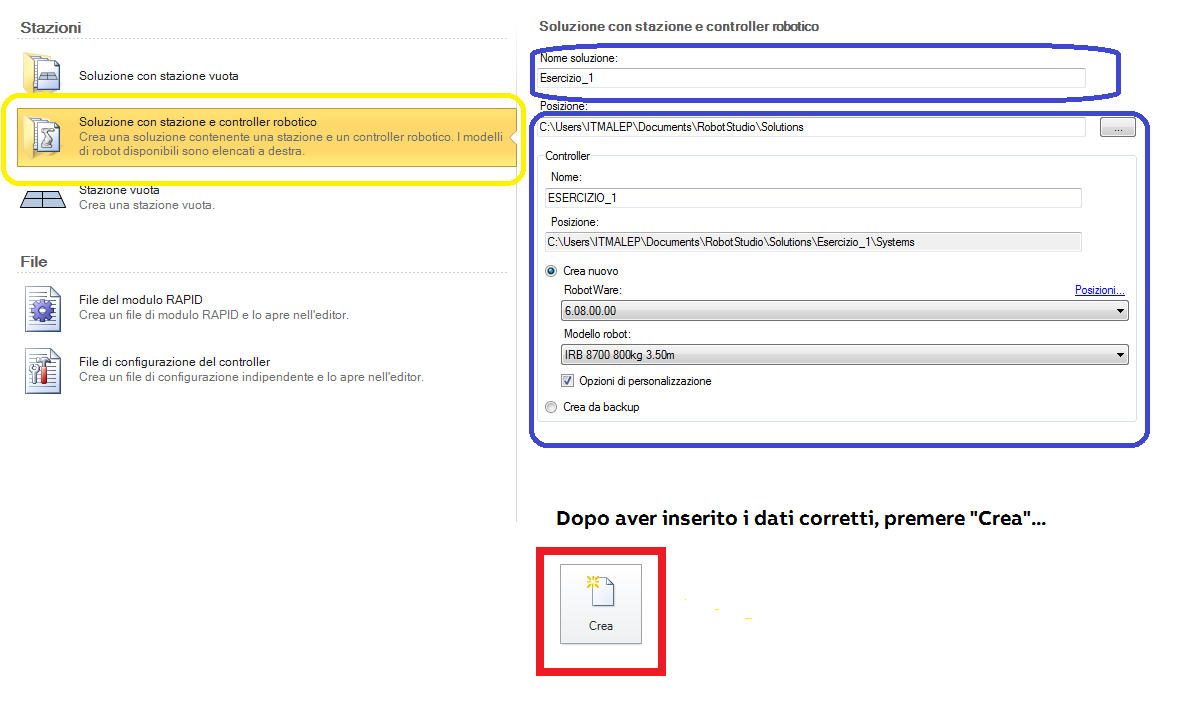
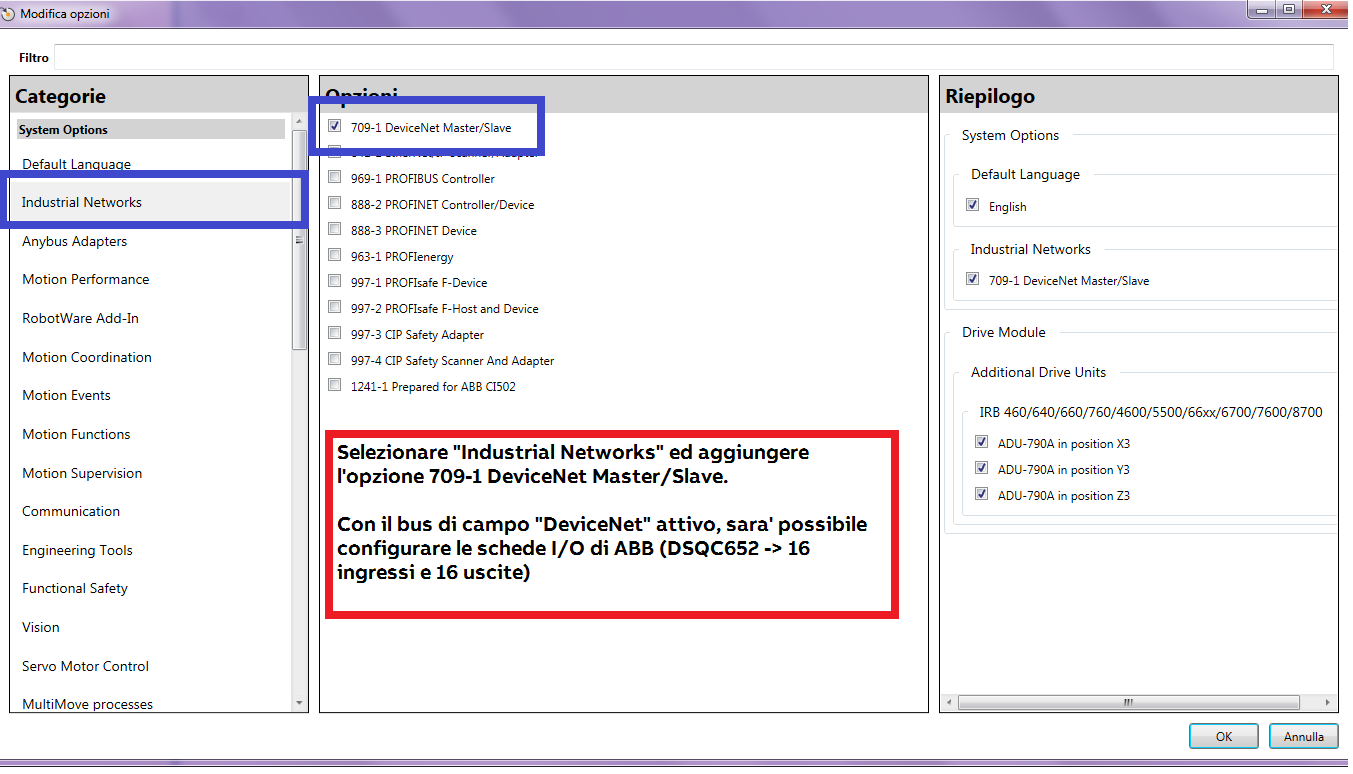
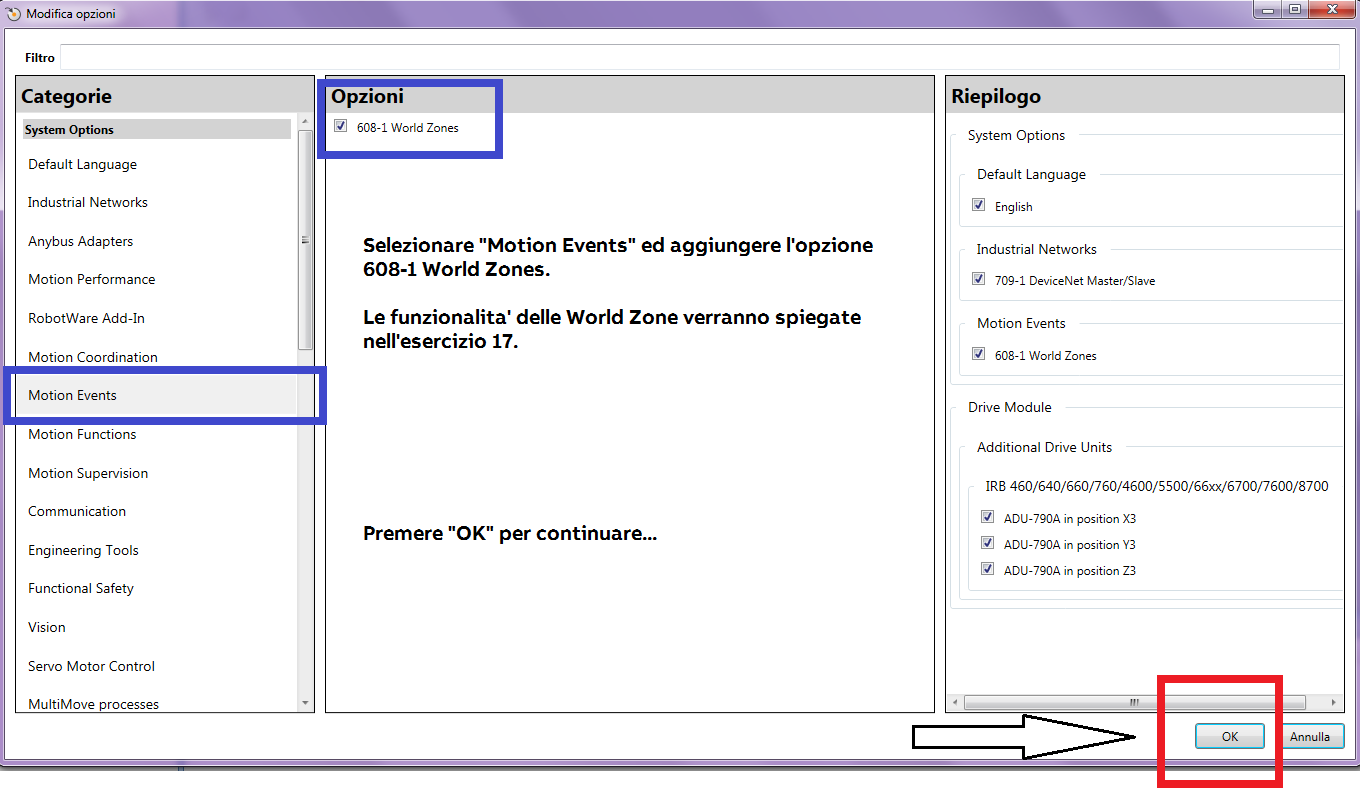
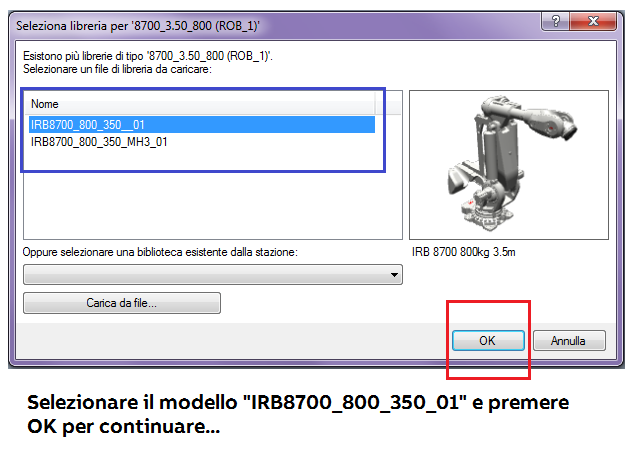
PROGETTO ABB/SCUOLE DISPENSA 1

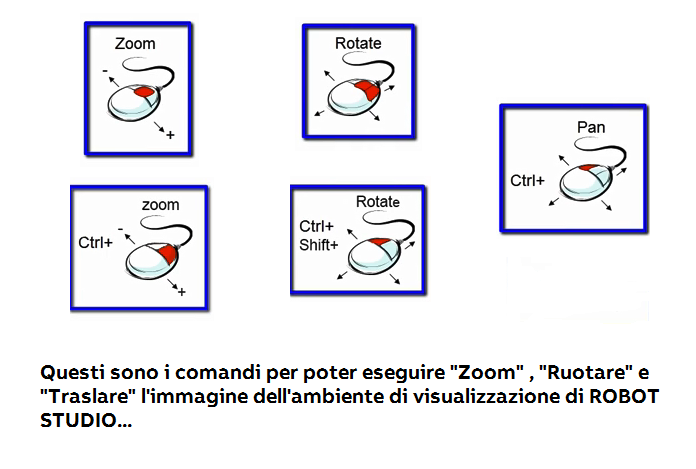


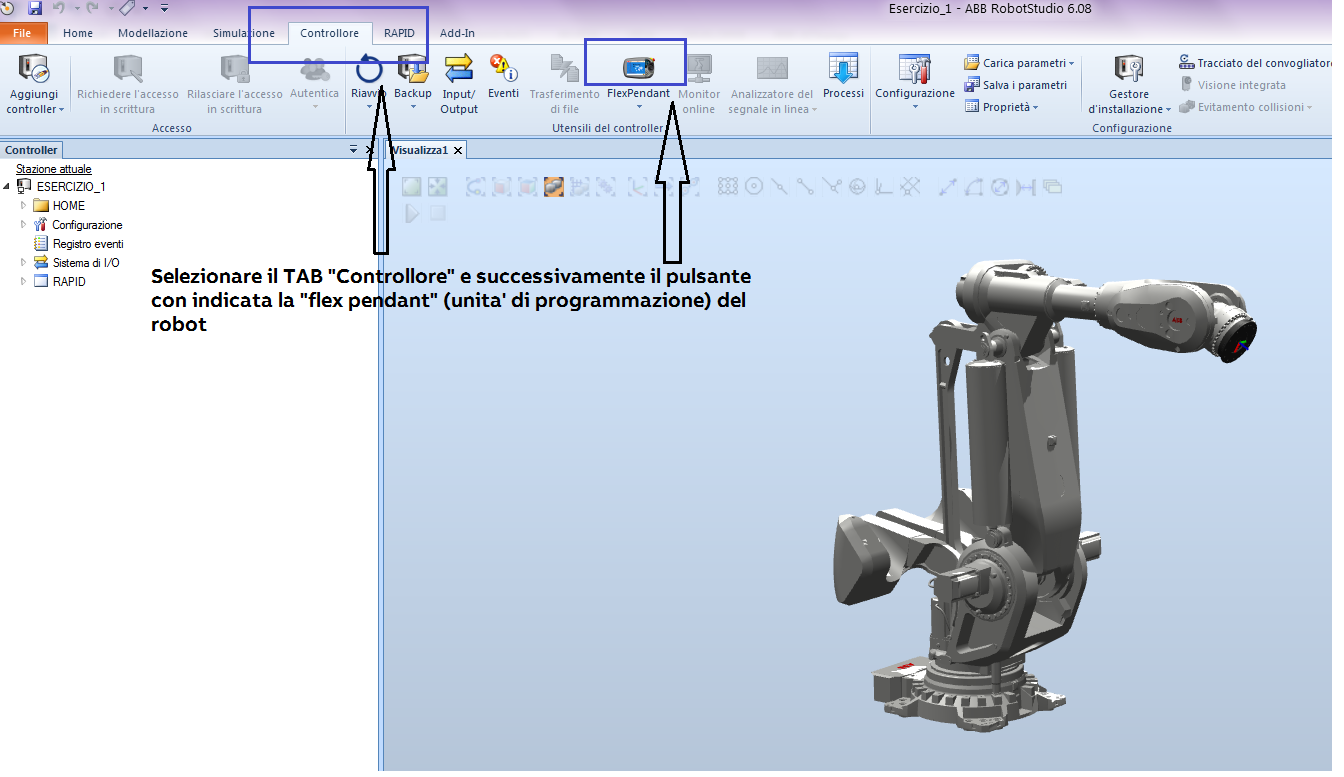


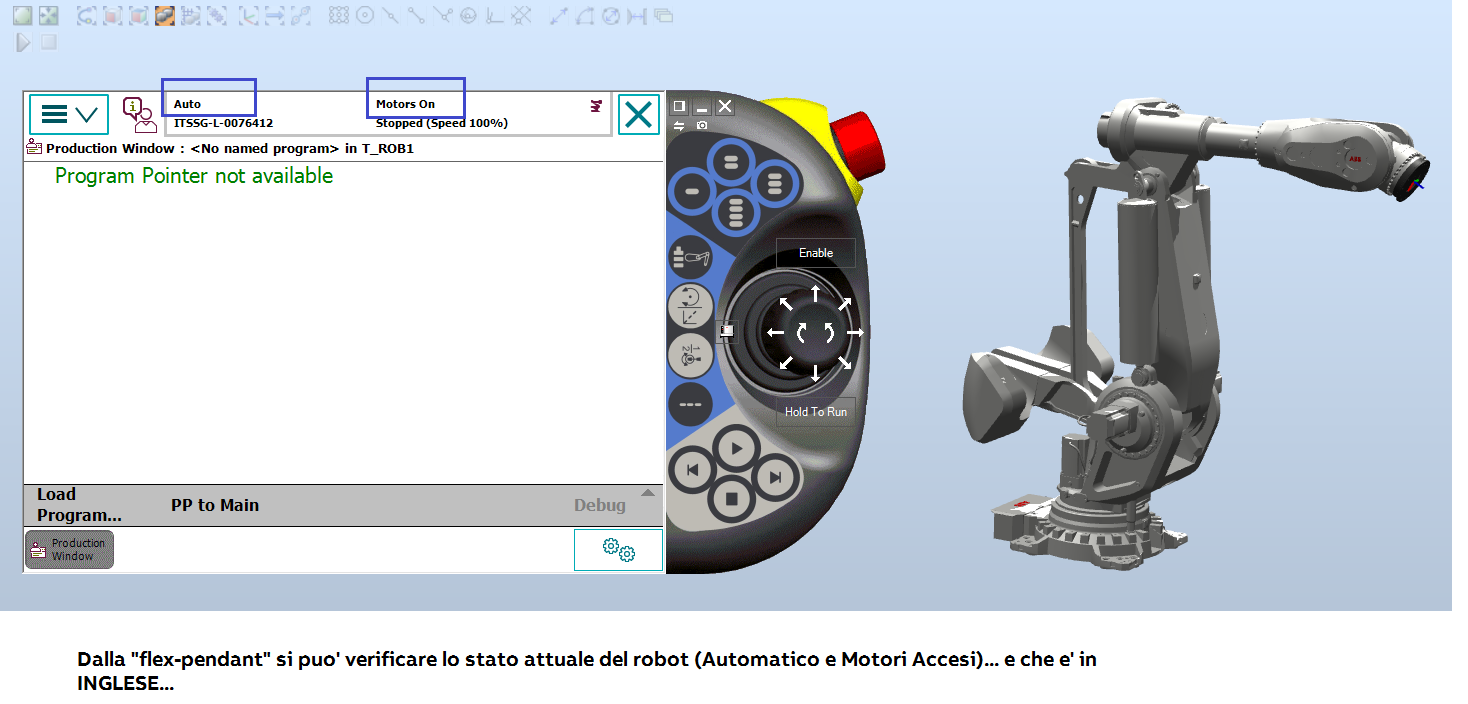












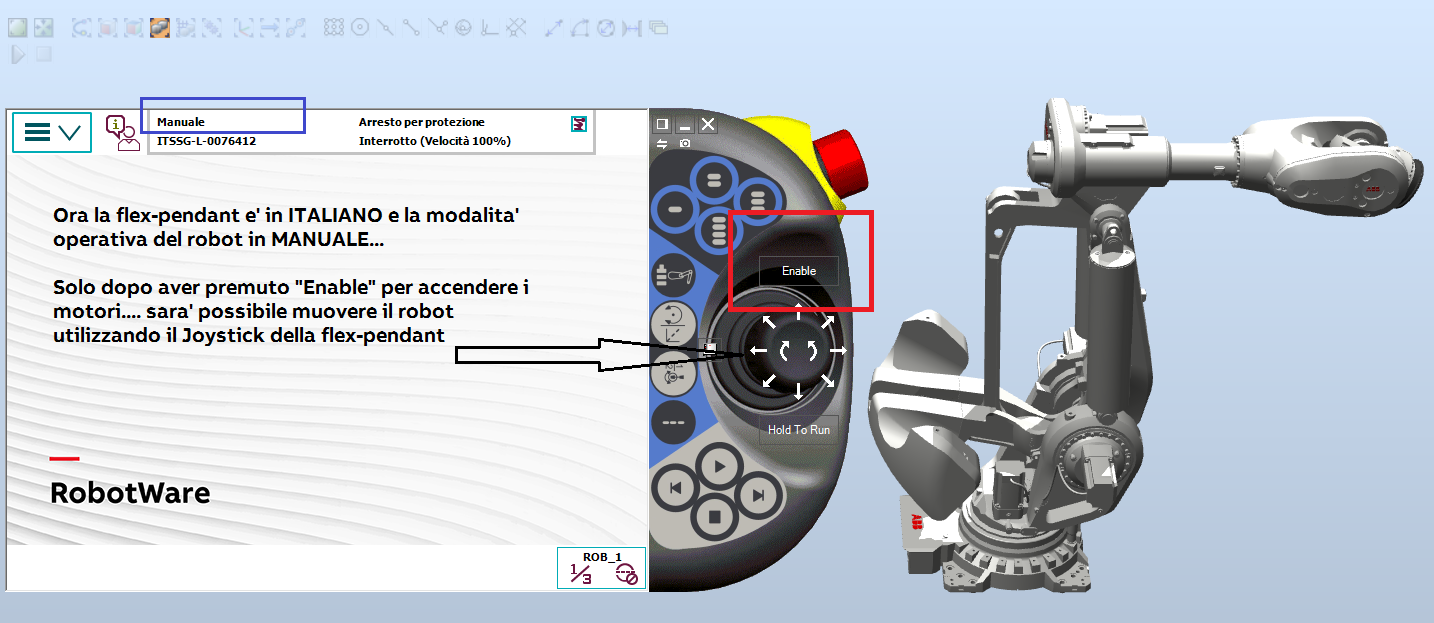
**Visualizzare I seguenti video per :**

1. **Cambiare la modalità da AUTOMATICO in MANUALE**
2. **Cambiare la lingua della flex-pendant da inglese in italiano**



[](file:///C:\Users\ITMALEP\AppData\Roaming\Microsoft\Word\DISPENSA_1\00%20_%20Come%20cambiare%20lingua%20unità%20di%20programmazione.flv)





**Descrizione dei seguenti video:**

* **Movimento singolo asse -> 1/3 oppure 4/6**
* **Movimento lineare / rio-rientamento rispetto alla base**
* **Movimento lineare / rio-rientamento rispetto al tool**
* **Riepilogo modalità movimento**

[](1A_MoveAxisByAxis.flv)

[](1B_LinearModeBase.flv)

[](1C_ReOrientLinearToolMode.flv)

[](03_%20Come%20muovere%20il%20robot%20usando%20il%20joystick.flv)

**Nel seguente video viene mostrato come aggiornare I parametri del robot, aggiungendo la scheda DSQC652.**

**In questo modo saranno configurati 16 ingressi e 16 uscite digitali (24 V).**

[](Come%20configuare%20scheda%20DSQC652%20.mp4)

